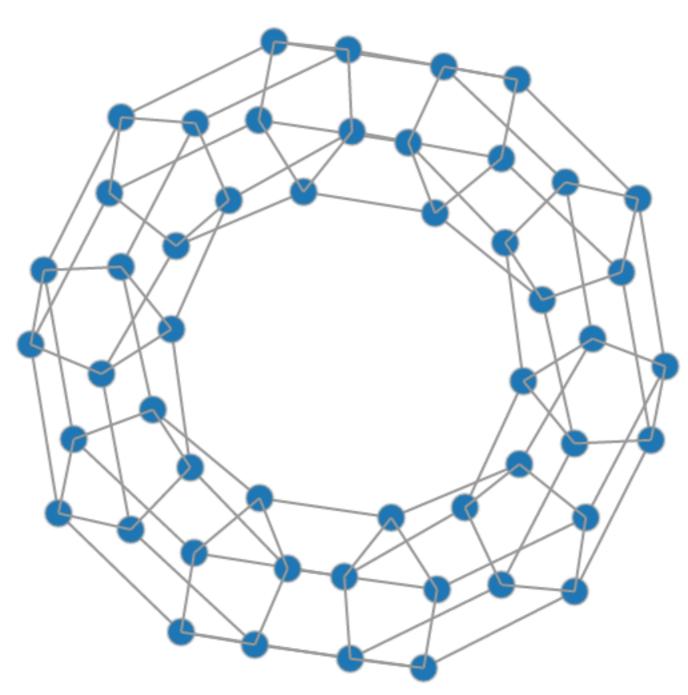
Graphs csc444

Node-link diagrams



http://christophermanning.org/gists/1703449/#/%5B10%5D50/1/0

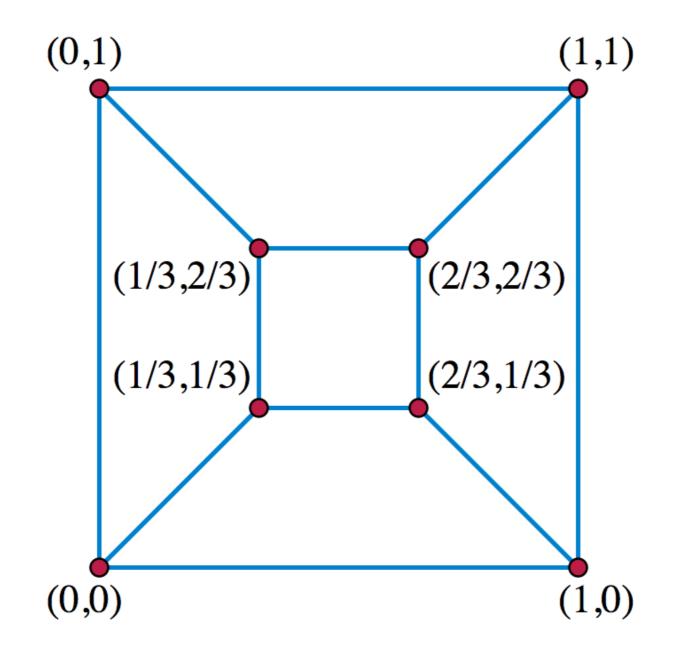
Starting simple: planar 3-vertex connected graphs (what?)

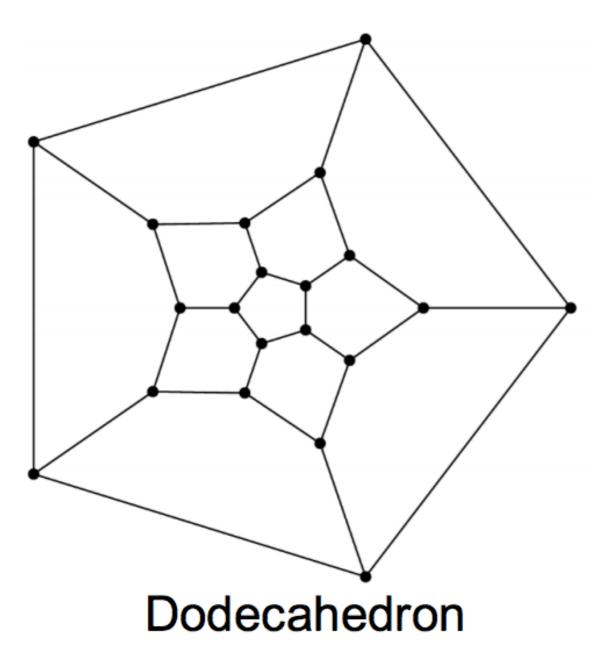
Tutte Embedding

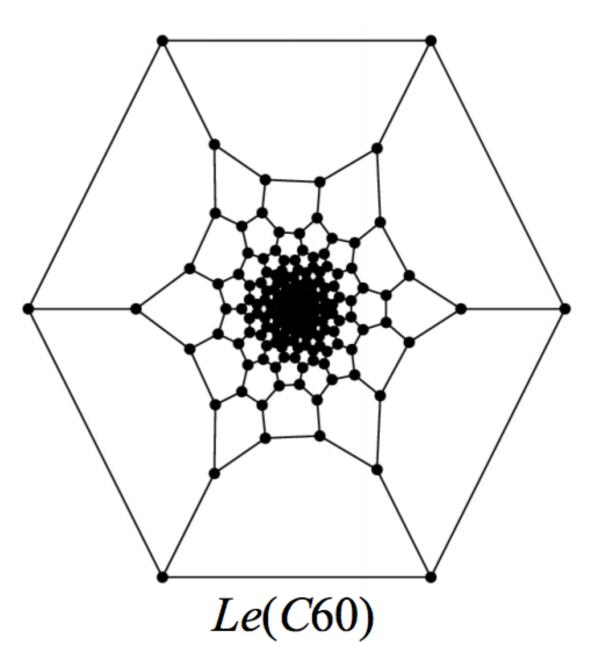
- Each node should be the average of its neighbors
 - Aside from the boundary, which is user-specified
- This gives a linear system of equations

 Theorem: if graph is planar, embedding is crossing-free

Tutte Embedding







http://www.cs.arizona.edu/~kpavlou/Tutte_Embedding.pdf

 Intuition: define "forces" on "physical objects", initialize positions randomly, let the system settle

http://bl.ocks.org/mbostock/4062045

 Need to define what forces are, and what physical objects are

- We want edges to be neither too small or too large
 - Aesthetic principle: graph neighbors should be close
 - Physical analogy: Springs compress or expand to achieve ideal length
- We don't want vertices to bunch up together
 - Aesthetic principle: position in screen should be unambiguous indicator of vertex identity
 - Physical analogy: Electric charges with the same sign don't bunch up

• Force per edge: $f_E(d) = C_E \times (d - L)$

• Force per vertex pair: $f_V(d) = C_V \times \frac{m_1 m_2}{d^2}$

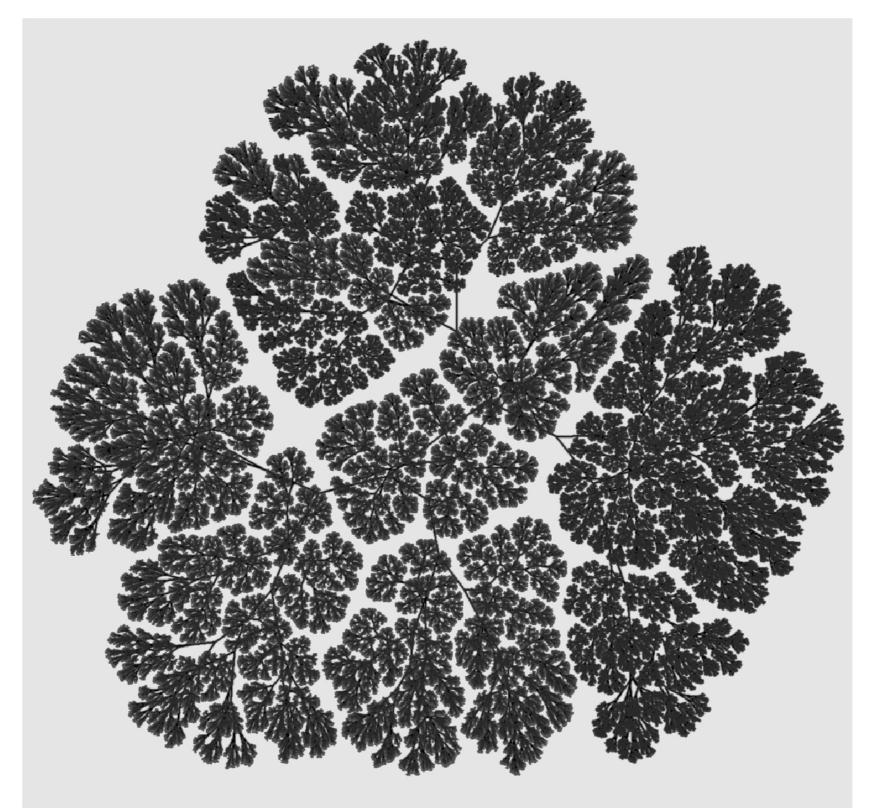
- Algorithm:
- For each vertex, determine all forces that apply to it,

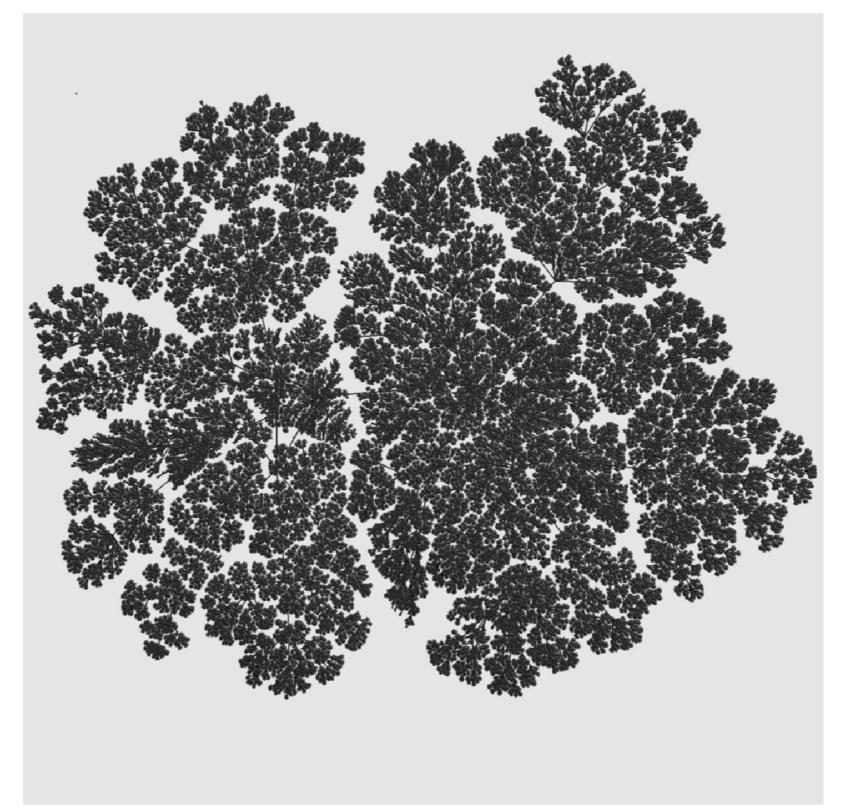
• Edges
$$f_E(d) = C_E \times (d - L)$$

• vertices
$$f_V(d) = C_V \times \frac{m_1 m_2}{d^2}$$

- compute direction of movement, move small amount in those directions
 - iterate until convergence

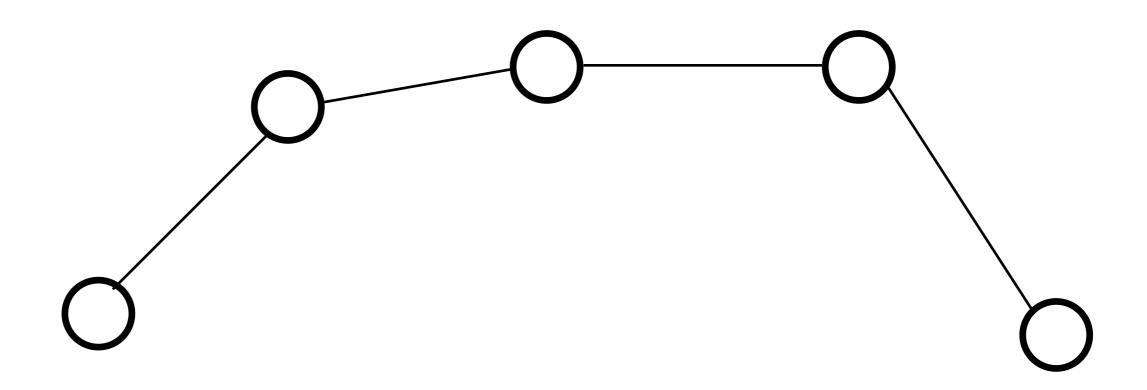
- Requires $O(|V|^2)$ work per step
 - Faster algorithms exist: Barnes-Hut, multipole methods, etc.
- For large graphs, result is not very informative



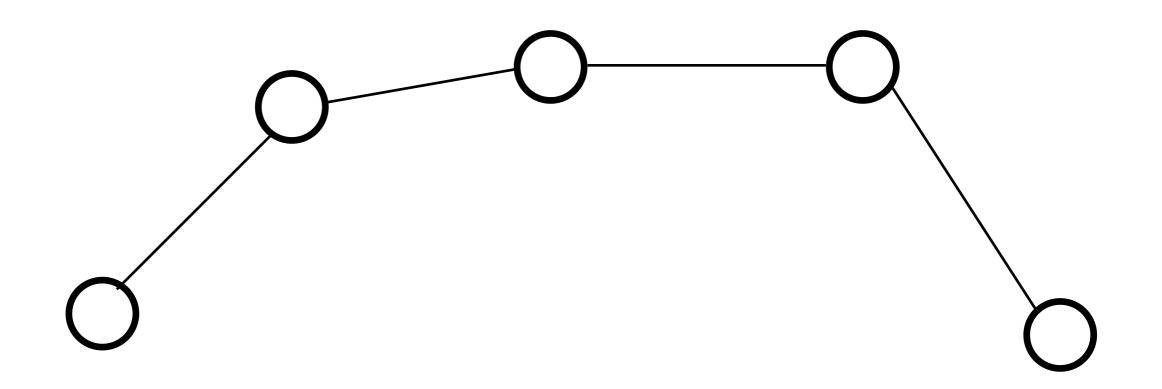


- Use global properties of the graph instead of only local interactions
- Specifically, graph distances

- Graph distances can be used to define "forces"
 - Encode directly that far away vertex pairs should be placed far from one another

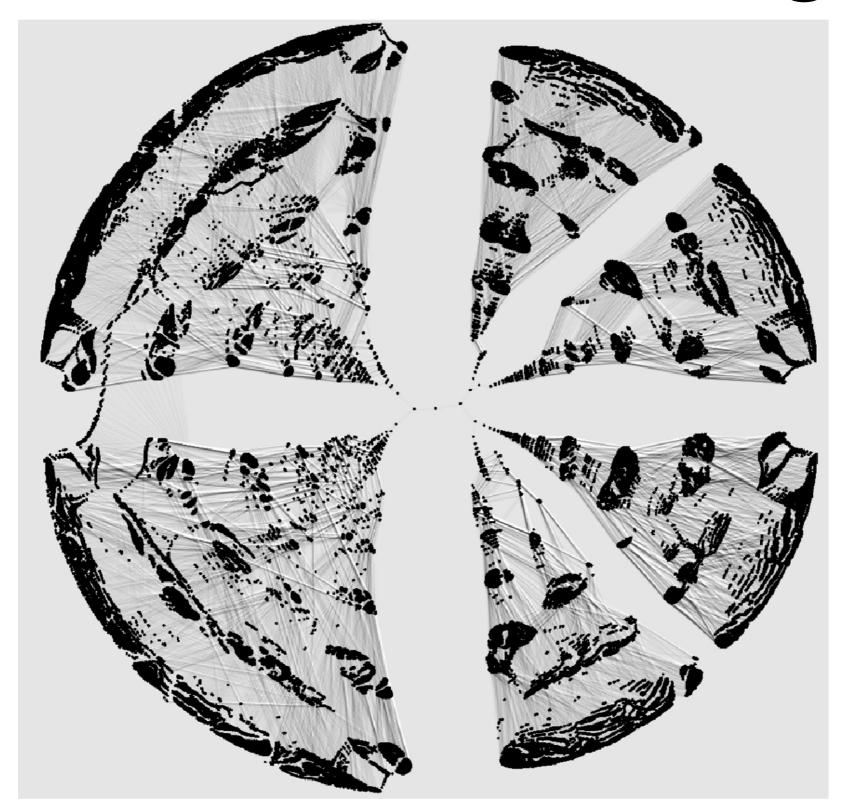


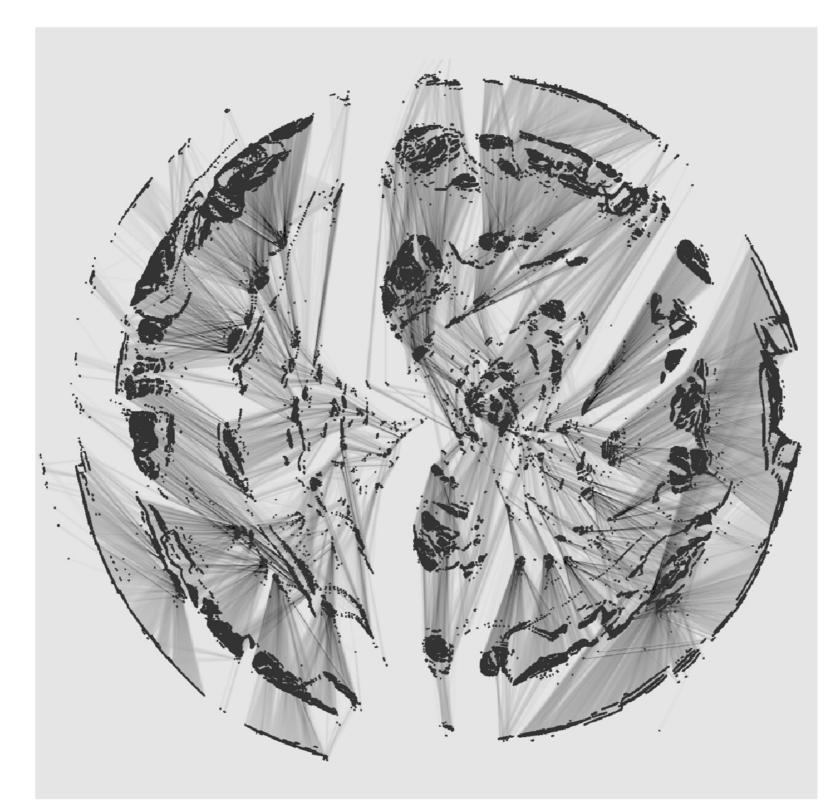
$$E(X) = \sum_{i,j} (d(i,j) - |X_i - X_j|)^2$$



$$E(X) = \sum_{i,j} (d(i,j) - |X_i - X_j|)^2$$

• Our old friend, dimensionality reduction!

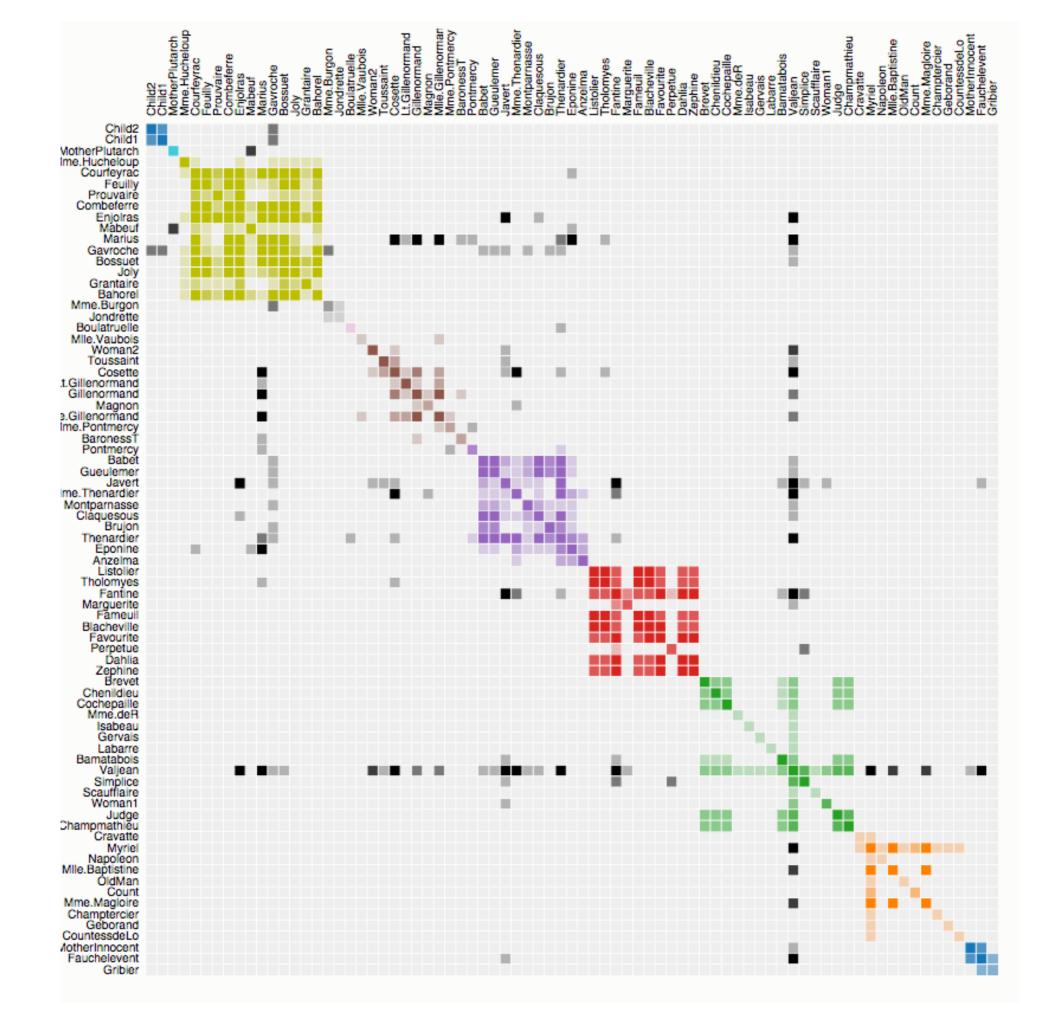




Matrix Diagrams

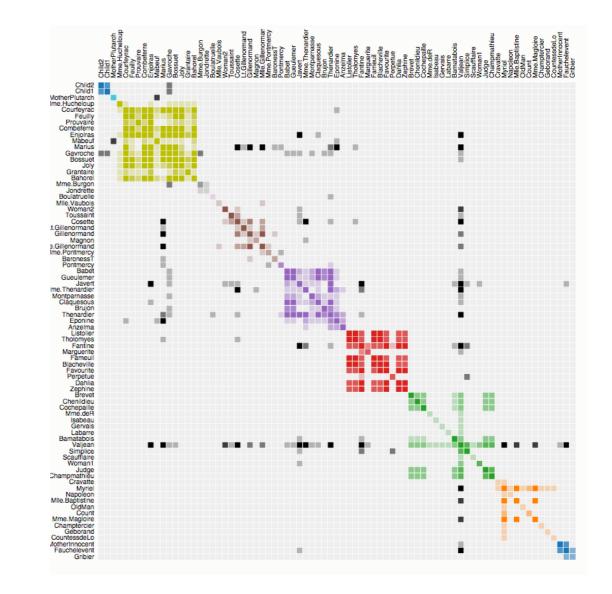
http://bost.ocks.org/mike/miserables/





Upsides

- Easy to define for directed and undirected graphs
- Easy to compute
- Easy to incorporate edge attributes



 The order in which rows are chosen makes a big impact in the visualization

